

Switches Representing by Unit Step

1. Introduction
 2. Signals
 3. Resistance
 4. Capacitance
 5. Inductance

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Pulse

1. Introduction
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$$P_{\Delta}(t) \equiv \begin{cases} 0 & t < 0 \\ 1/\Delta & t = 0 \\ 0 & t > 0 \end{cases}$$

$$P_{\Delta}(t) = \frac{1}{\Delta} \{u(t) - u(t - \Delta)\}$$

Write $P_{\Delta}(t)$ in terms of $u_{\epsilon}(t)$

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Unit Impulse

1. Introduction
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Dirac delta function

$$\delta(t) \equiv \begin{cases} 0 & t \neq 0 \\ ?(\infty) & t = 0 \end{cases}$$

such that $\forall \xi: \int_{-\xi}^{+\xi} \delta(t) dt = 1$

$$\delta(t) = \lim_{\Delta \rightarrow 0} P_{\Delta}(t)$$

Paul Dirac (1902-1984)

$$u(t) = \int_{-\infty}^t \delta(\epsilon) d\epsilon$$

$$\delta(t) = \frac{du(t)}{dt}$$

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Unit Impulse

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Some properties:

$$\delta(t)x(t) = \delta(t)x(0)$$

$$\delta(at) = \frac{1}{|a|}\delta(t) \quad \delta(-t) = \delta(t)$$

Sampling Property:

$$x(0) = \int_{-\infty}^{+\infty} x(t)\delta(t)dt \rightarrow x(t_0) = \int_{-\infty}^{+\infty} x(t)\delta(t - t_0)dt$$

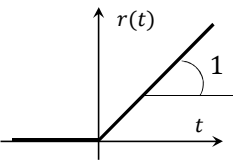
$$\int_{-\infty}^{+\infty} x(t)\delta(t)dt = \int_{-\infty}^{+\infty} x(0)\delta(t)dt = x(0) \int_{-\infty}^{+\infty} \delta(t)dt = x(0)$$

$$x(t) = \int_{-\infty}^{+\infty} x(\tau)\delta(\tau - t)d\tau$$

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Unit Ramp

1. Introduction
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$$r(t) = tu(t)$$

$$u(t) = \int_{-\infty}^t \delta(\tau) d\tau \qquad r(t) = \int_{-\infty}^t u(\tau) d\tau$$

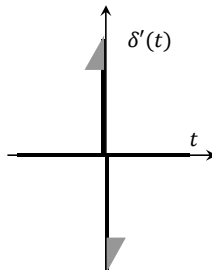
$$\delta(t) = \frac{du(t)}{dt} \qquad u(t) = \frac{dr(t)}{dt}$$

$$\int_{-\infty}^t u(\tau) d\tau = r(t) \qquad \int_{-\infty}^t r(\tau) d\tau = \frac{1}{2}r(t)^2$$

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Unit Doublet

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$$\delta(t) \equiv \begin{cases} 0 & t \neq 0 \\ ? & t = 0 \end{cases}$$

such that $\int_{-\infty}^t \delta'(\tau) d\tau = \delta(t)$

$$\delta'(t) = \frac{d\delta}{dt}$$


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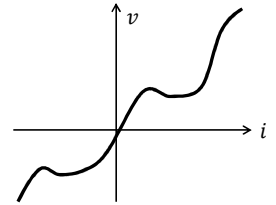
Resistance

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Resistance

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Definition:  $v(t) \equiv \hat{G}(i(v))$ conductance



- { TI: Time Independent
- { TD: Time Dependent
- { L: Linear
- { NL: Non-linear

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Resistance - LTI

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LTI

- { TI: Time Independent
- { TD: Time Dependent
- { L: Linear
- { NL: Non-linear

Resistance

LTI: $\begin{cases} v(t) = R i(t) \\ i(t) = G v(t) \end{cases}$

Conductance

Only mathematical abstraction

Extreme cases: $\begin{cases} R = 0 & \text{Short circuit} \\ G = 0 & \text{Open circuit} \end{cases}$

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Resistance - LTD

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LTD: Linear Time Dependent

Can be used for modulation

$R(t) \propto \sin \omega_1 t$
 $I_s = i(t) \propto \sin \omega_2 t$ } $\rightarrow v(t) \propto \sin(\omega_1 \pm \omega_2)t$

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Resistance - NLTI

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NLTI: Diode

$i(t) = I_s (e^{qv(t)/nkT} - 1)$

$V_T = \frac{kT}{q} \Big|_{300^\circ K} = 26mV$

$i(t) = I_s (e^{v(t)/nV_T} - 1)$ $n = 1 \dots 2$

voltage controlled current controlled both

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Resistance - NL

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unilateral

bilateral

$i = f(v)$
 $-i = f(-v)$

all linear Resistors

conditional function $\begin{cases} 1 & \text{short circuit ; } v = 0 & \text{if } i \geq 0 \\ 2 & \text{open circuit ; } i = 0 & \text{if } v \leq 0 \end{cases}$

Ideal approximation: neither voltage controlled nor current controlled

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Resistance – NL – Voltage Source

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Resistance – NL – Current Source

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Reminder – Thevenin, Norton

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Linear Circuit

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Linear 2-terminal network

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Capacitor

1. Introduction

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3. Resistance

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Capacitance

1. Introduction

2. Signals

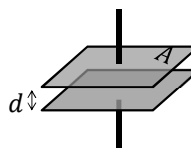
3. Resistance


4. Capacitance

5. Inductance

capacitor $q(t) \equiv \hat{C}(v(t))$

Stores energy in form of electric field \mathcal{E}



$$C = \epsilon \frac{A}{d}$$


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Capacitance

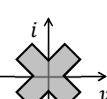
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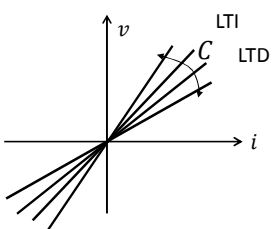
Definition: $q(t) \equiv \hat{C}(v(t))$
capacitance


Whatever we said about $i - v$ (resistance) can be repeated here about $q - v$ (capacitance)

{ TI: Time Independent
TD: Time Dependent

{ L: Linear
NL: Non-linear

application:





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Capacitance

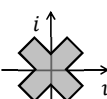
1. Introduction

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LTI $q(t) = Cv(t)$ C : Capacitance [F] [μ F]

$i(t) = \frac{dq}{dt} = C \frac{dv(t)}{dt}$ memory!

$\hookrightarrow v(t) = v(0) + \frac{1}{C} \int_0^t i(t') dt'$

Big?: linear or nonlinear

Definition of linear function: $\begin{cases} f(ax) = af(x) \\ f(x_1 + x_2) = f(x_1) + f(x_2) \end{cases}$

linear only if $v(0) = 0$

$$v(t) = \frac{1}{C} \int_0^t i(t') dt'$$

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Capacitance - Example

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$v(0) = 0$

Repeat this for $V(0) = 2V$
What is the difference?

Slope = 2

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Capacitance - Thevenin, Norton

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$v(0) = V_0$

$v(0) = 0$

$v(0) = 0$

$$v(t) = v(0) + \frac{1}{C} \int_0^t i(t') dt'$$

series V_0

Thevenin

Norton

$$v_s(t) = \frac{1}{C} \int_0^t i_s(t') dt'$$

$$i_s(t) = C \frac{dv_s(t)}{dt}$$

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Capacitance - Switches

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$v_1(0) = V_0$ $v_2(0) = 0$

$v_1(0^+) = v_2(0^+) = V = ?$ KCL

$$v(t) = v(0) + \frac{1}{C} \int_0^t i(t') dt' \quad i_1 = \alpha \delta(t) = -i_2$$

$$v_1(0^+) = v_1(0^-) + \frac{1}{C_1} \int_{0^-}^{0^+} i_1(t') dt' = V_0 + \frac{\alpha}{C_1} = V = 0 - \frac{\alpha}{C_2}$$

$$\alpha = \frac{-C_1 C_2}{C_1 + C_2} V_0 \quad V = \frac{C_1}{C_1 + C_2} V_0$$

$$v(0^+) = \frac{1}{C_1 + C_2} \int_{0^-}^{0^+} C_1 V_0 \delta(t) dt'$$

$$= \frac{C_1}{C_1 + C_2} V_0$$

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Example

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$t = 0^-$

$t = 0^-$

$t = 0^+$

$$v = 0 + \frac{\alpha_2}{3} = 4 + \frac{\alpha_3}{2} = v_2(0^+) = v_3(0^+)$$

$$v_1(0^+) = 10 - v = \frac{\alpha_2 + \alpha_3}{2}$$

$$v_2(0^+) = v_3(0^+) = \frac{28}{7} \quad v_1(0^+) = \frac{42}{7}$$

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Inductance - Thevenin , Norton

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$i(0) = I_0 \downarrow \Rightarrow L \quad v \quad \equiv \quad I_0 \downarrow \Rightarrow L \quad v \quad \equiv \quad L I_0 \delta(t) \downarrow \Rightarrow L \quad v$

$$i(t) = i(0) + \frac{1}{L} \int_0^t v(t') dt'$$

parallel $\underbrace{\hspace{10em}}$
 I_0

Thevenin / Norton

$i_s(t) = \frac{1}{L} \int_0^t v_s(t') dt'$

$v_s(t) = L \frac{di_s(t)}{dt}$

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Inductance - LTD

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LTD: $\varphi(t) = L(t)i(t)$

$$v(t) = \frac{d\varphi}{dt}$$

$$= L(t) \frac{di(t)}{dt} + \frac{dL(t)}{dt} i(t)$$

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