Communication Channels

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Communication Channels

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- Ideal channel
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- Additive white Gaussian noise channel
- Solution Linear filter additive white Gaussian noise channel
- Iinear filter additive colored Gaussian noise channel
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Figure: Ideal channel.

$$y(t)=x(t)$$

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Attenuation channel



Figure: Attenuation channel.

y(t) = Ax(t)

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Distortion-less channel



Figure: Distortion-less channel.

$$y(t) = Ax(t-D)$$

Linear filter channel



Figure: Linear filter channel.

$$y(t) = x(t) * h(t)$$

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Figure: Additive white Gaussian noise channel.

$$y(t) = x(t) + n(t)$$

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Linear filter additive white Gaussian noise channel



Figure: Linear filter additive white Gaussian noise channel.

$$y(t) = x(t) * h(t) + n(t)$$

Linear filter additive colored Gaussian noise channel



Figure: Linear filter additive colored Gaussian noise channel.

$$y(t) = [x(t) * h_1(t) + n(t)] * h_2(t) = x(t) * h_1(t) * h_2(t) + n(t) * h_2(t)$$

Nonlinear noisy channel



Figure: Nonlinear noisy channel.

$$y(t) = T\{x(t), n(t)\}$$

Channel Modeling

Example (Linear filter channel)

A point-to-point microwave radio channel can be modeled as a linear filter channel with the impulse response $h(t) = A_1\delta(t - D_1) + A_2\delta(t - D_2)$



Figure: Point-to-point microwave radio channel.

$$y(t) = A_1 x(t - D_1) + A_2 x(t - D_2)$$

$$y(t) = x(t) * [A_1 \delta(t - D_1) + A_2 \delta(t - D_2)] = x(t) * h(t)$$

Channel Modeling

Example (Linear filter AWGN channel)

A noisy point-to-point microwave radio channel can be modeled as a linear filter additive white Gaussian noise channel with the impulse response $h(t) = A_1\delta(t-D_1) + A_2\delta(t-D_2)$ and additive white Gaussian noise process n(t).



Figure: Noisy point-to-point microwave radio channel.

$$y(t) = A_1 x(t - D_1) + A_2 x(t - D_2) + n(t)$$

$$y(t) = x(t) * [A_1 \delta(t - D_1) + A_2 \delta(t - D_2)] + n(t) = x(t) * h(t) + n(t)$$

Example (Nonlinear channel)

Square-law photo-detector can be modeled as a nonlinear channel with the transformation $i(t) = \eta |E(t)|^2$.



Figure: Photodetector.

$$i(t) = \eta |E(t)|^2$$
$$y(t) = \eta |x(t)|^2$$

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