

Digital Communication

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- 1 Digital Communication
- 2 Baseband Digital Transmission
- 3 Passband Digital Transmission

Digital Communication

Advantages and Disadvantages

- ✓ Hardware **stability**.
- ✓ Operational **flexibility**.
- ✓ Reliable **reproduction**.
- ✓ Noise **immunity**.
- ✗ **Complex** implementation.

1 Baseband digital transmission

- 1 Lowpass channel.
- 2 Carrier-less.
- 3 Usually short distance.
- 4 Usually wired.

2 Passband digital transmission

- 1 Bandpass channel.
- 2 Carrier-oriented.
- 3 Usually long distance.
- 4 Usually wireless.

Baseband Digital Transmission

Statement (Digital Pulse Amplitude Modulation Signal)

A digital pulse amplitude modulation signal is expressed as

$$x(t) = \sum_{k=-\infty}^{\infty} a_k p(t - kD)$$

, where the k th symbol a_k belongs to a set of $M = 2^n$ levels and $p(t)$ is a pulse that satisfies the condition

$$p(KD) = \begin{cases} 1, & K = 0 \\ 0, & K = \pm 1, \pm 2, \dots \end{cases}$$

✓ Clearly, $x(KD) = \sum_{k=-\infty}^{\infty} a_k p(KD - kD) = a_K$.

Baud Rate and Bit Rate

Definition (Baud Rate)

The baud or symbol rate of a PAM signal is defined as

$$r = \frac{1}{D}$$

Definition (Bit Rate)

The bit rate of a PAM signal is defined as

$$r_b = r \log_2(M) = \frac{\log_2(M)}{D} = \frac{n}{D} = rn$$

Binary PAM formats with rectangular pulses

- 1 Unipolar return to zero with $p(t) = \Pi(\frac{t}{D/2})$ and $a_k = b_k A$.
 - 2 Unipolar nonreturn to zero with $p(t) = \Pi(\frac{t}{D})$ and $a_k = b_k A$.
 - 3 Polar return to zero with $p(t) = \Pi(\frac{t}{D/2})$ and $a_k = (b_k - 0.5)A$.
 - 4 Polar nonreturn to zero with $p(t) = \Pi(\frac{t}{D})$ and $a_k = (b_k - 0.5)A$.
 - 5 Twinned binary with $p(t) = \Pi(\frac{t}{D/2}) - \Pi(\frac{t-D/2}{D/2})$ and $a_k = (b_k - 0.5)A$.
- ✓ The formats differ in DC value, power, power spectral density, and synchronization.

Line Codes

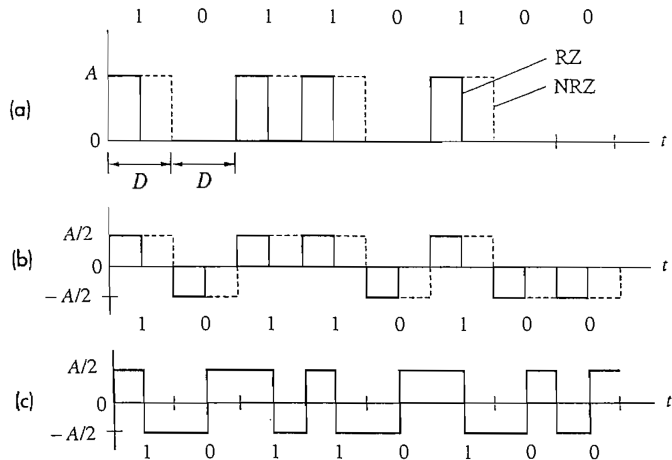


Figure: Binary PAM formats with rectangular pulses (line codes). (a) Unipolar RZ and NRZ (b) Polar RZ and NRZ (c) Twined binary.

M-ary Line Codes

Polar quaternary nonreturn to zero with $p(t) = \Pi(\frac{t}{D})$ and symbols a_k as

a_k	NBC Code	Gray Code
$3A/2$	11	10
$A/2$	10	11
$-A/2$	01	01
$-3A/2$	00	00

Table: Symbols in polar quaternary NRZ.

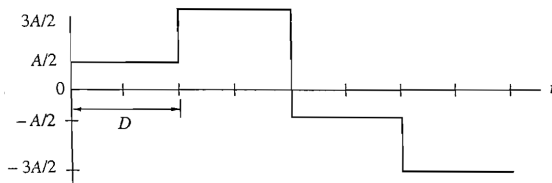


Figure: Polar quaternary NRZ.

Statement (Power Spectral Density of PAM)

Power spectral density of the pulse amplitude modulation signal $x(t) = \sum_{k=-\infty}^{\infty} a_k p(t - kD)$ is

$$S_x(f) = \frac{1}{D} |P(f)|^2 \sum_{n=-\infty}^{\infty} R_a[n] e^{-j2\pi n f D}$$

, where $P(f)$ is the Fourier transform of $p(t)$ and $R_a[n] = E\{a_{n+k} a_k\}$ is the autocorrelation of the stationary discrete random process a_k .

✓ If a_k is a zero-mean uncorrelated discrete random process, $S_x(f) = \frac{R_a[0]}{D} |P(f)|^2$.

PSD of PAM

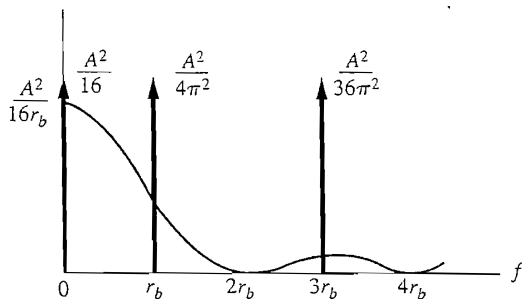


Figure: Power spectra density of unipolar binary RZ.

Eye Diagram

$$y(t_K) = a_K \underbrace{\tilde{p}(t_s)}_{\text{Synchronization Mismatch}} + \underbrace{\sum_{k \neq K}^{\infty} a_k \tilde{p}(KD + t_s - kD)}_{\text{Inter-Symbol Interference}} + \underbrace{n(t_K)}_{\text{Noise}}$$

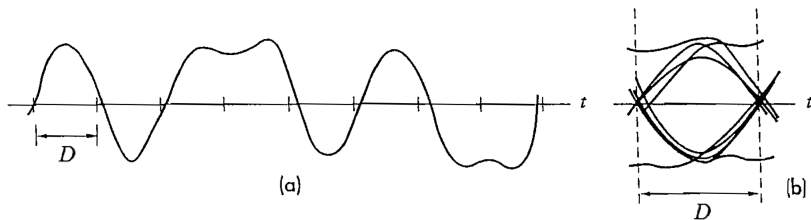


Figure: (a) Distorted polar binary signal (b) Eye diagram.

Eye Diagram

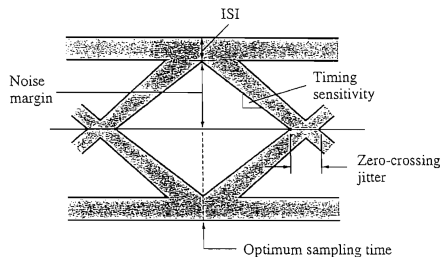


Figure: Binary eye pattern.

- 1 Inter-symbol interference
- 2 Optimum sampling time
- 3 Zero-crossing jitter
- 4 Noise margin
- 5 Timing sensitivity
- 6 Nonlinear distortion

Synchronization Mismatch and ISI

Statement (Suitable Synchronization)

A suitable synchronization can mitigate or eliminate synchronization mismatch. Zero-crossing in PAM signal has a key role in synchronization.

Statement (ISI Cancellation)

Given an ideal lowpass channel of bandwidth B , it is possible to transmit independent symbols at a rate $r \leq 2B$ baud without ISI. It is not possible to transmit independent symbols at $r > 2B$.

✓ Signaling at the maximum rate $r = 2B$ requires since pulse shaping $p(t) = \text{sinc}(rt)$.

Bit Error Probability

Statement (Bit Error Probability of Unipolar NRZ)

Assuming perfect ISI cancellation and synchronization, the bit error probability for unipolar NRZ binary signaling in zero-mean Gaussian noise with variance σ^2 is $P_e = Q(A/(2\sigma))$, where $Q(x)$ is the tail distribution function of the standard normal distribution, and 0 and A are the symbols corresponding to the equally-probable binary digits 0 and 1.

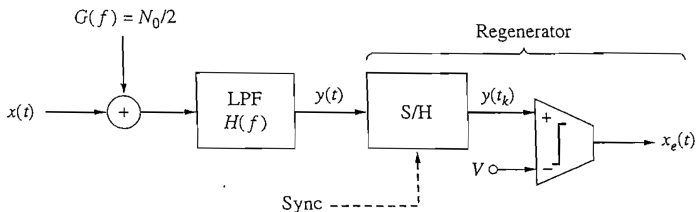


Figure: Baseband binary receiver.

Bit Error Probability

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Assuming perfect ISI cancellation and synchronization, the bit error probability for unipolar NRZ binary signaling is $P_e = Q(A/(2\sigma))$.

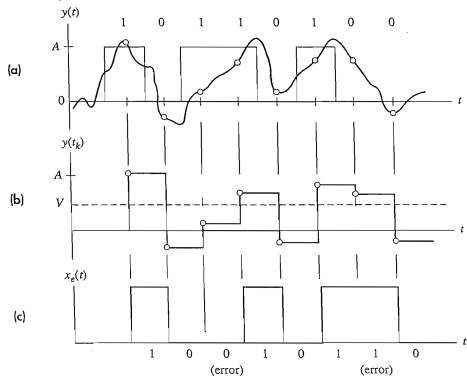


Figure: A unipolar NRZ signal (a) signal plus noise (b) S/H output (c) Comparator output.

Statement (Bit Error Probability of Unipolar NRZ)

Assuming perfect ISI cancellation and synchronization, the bit error probability for unipolar NRZ binary signaling is $P_e = Q(A/(2\sigma))$.

$$\begin{aligned}P_e &= P_0 P_{e|0} + P_1 P_{e|1} = \frac{1}{2}(P_{e|0} + P_{e|1}) \\&= \frac{1}{2}(P[y(t_K) > V | a_K = 0] + P[y(t_K) \leq V | a_K = A]) \\&= \frac{1}{2}(P[n(t_K) > V | a_K = 0] + P[n(t_K) + A \leq V | a_K = A]) \\&= \frac{1}{2}\left(Q\left(\frac{V}{\sigma}\right) + Q\left(\frac{A - V}{\sigma}\right)\right)\end{aligned}$$

$$\frac{dP_e}{dV} = 0 \Rightarrow V = \frac{A}{2} \Rightarrow P_{e_{\min}} = Q\left(\frac{A}{2\sigma}\right)$$

Passband Digital Transmission

Common passband digital transmission techniques

- 1 Amplitude Shift Keying (**ASK**)
- 2 Phase Shift Keying (**PSK**)
- 3 Frequency Shift Keying (**FSK**)

Passband Transmission Techniques

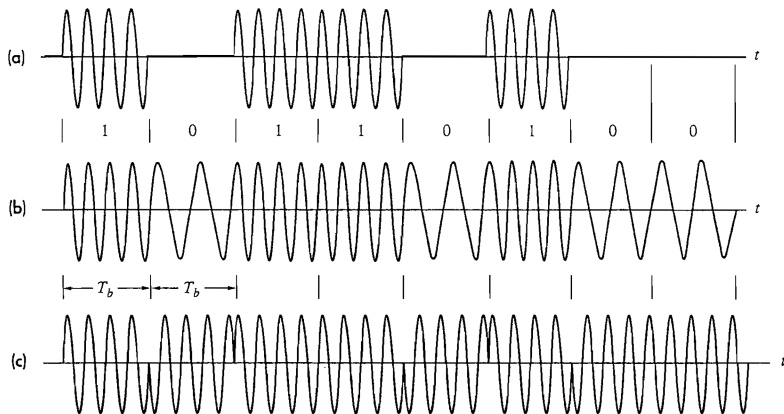


Figure: Binary modulated waveforms (a) ASK (b) FSK (c) PSK.

Statement (Passband Digital Signal)

Any modulated passband signal may be expressed in the quadrature-carrier form

$$x(t) = A_c[x_i(t) \cos(2\pi f_c t + \theta) - x_q(t) \sin(2\pi f_c t + \theta)]$$

. The carrier frequency f_c , amplitude A_c , and phase θ are constant, while the time-varying in-phase $x_i(t)$ and quadrature $x_q(t)$ components contain the message.

Statement (PSD of Passband Digital Signal)

Power spectral density of the passband digital signal $x(t) = A_c[x_i(t) \cos(2\pi f_c t + \theta) - x_q(t) \sin(2\pi f_c t + \theta)]$ is

$$S_x(f) = \frac{A_c^2}{4} [S_{x_i}(f - f_c) + S_{x_i}(f + f_c) + S_{x_q}(f - f_c) + S_{x_q}(f + f_c)]$$

, where $S_{x_i}(f)$ and $S_{x_q}(f)$ are the power spectral density of the in-phase and quadrature components, respectively.

PSD of Passband Digital Signal

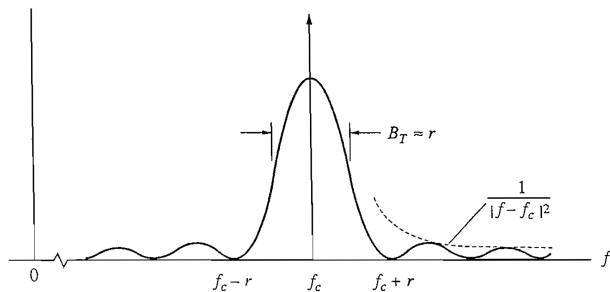


Figure: Power spectra density of ASK.

Statement (ASK)

In ASK,

$$x_i(t) = \sum_k a_k p(t - kD), \quad x_q(t) = 0$$

$$a_k = 0, 1, \dots, M - 1$$

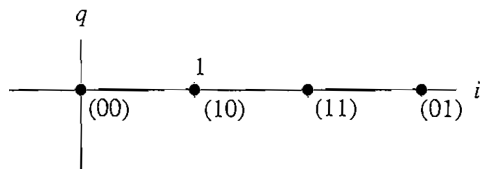


Figure: ASK constellation.

Statement (PSK)

In PSK,

$$x_i(t) = \sum_k \cos(\phi_k) p(t - kD), \quad x_q(t) = \sum_k \sin(\phi_k) p(t - kD)$$

$$\phi_k = \pi(2a_k + 1)/M, \quad a_k = 0, 1, \dots, M - 1$$

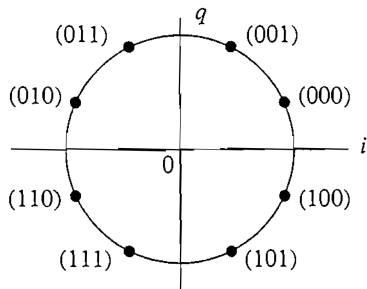


Figure: PSK constellation.

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