

Question 1

For the circuit shown in Fig. 1,

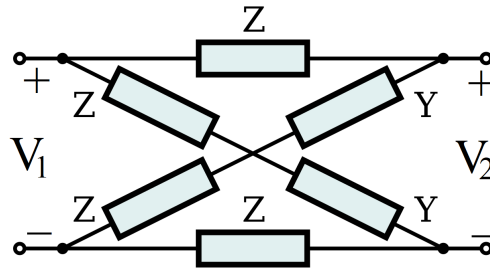


Figure 1: Lattice network.

(a) Find the network function $H(j\omega) = \frac{V_2(j\omega)}{V_1(j\omega)}$, where $Z(j\omega)$ and $Y(j\omega)$ denote impedance and admittance of the diagonal single-port passive networks.

$$V_2(j\omega) = \frac{Y^{-1} + Z}{Y^{-1} + Z + Z} V_1(j\omega) - \frac{Z}{Y^{-1} + Z + Z} V_1(j\omega) = \frac{Y^{-1}}{Y^{-1} + 2Z} V_1(j\omega) = \frac{1}{1 + 2ZY} V_1(j\omega)$$

So,

$$H(j\omega) = \frac{V_2(j\omega)}{V_1(j\omega)} = \frac{1}{1 + 2Z(j\omega)Y(j\omega)}$$

(b) Let $Z(j\omega) = j\omega + \frac{1}{j\omega}$ and $Y(j\omega) = j\omega + \frac{1}{j\omega}$ be a series and a parallel LC network, respectively. Find the simplified transfer function $H(j\omega) = \frac{V_2(j\omega)}{V_1(j\omega)}$ and the corresponding amplitude and phase responses.

$$H(j\omega) = \frac{V_2(j\omega)}{V_1(j\omega)} = \frac{1}{1 + 2Z(j\omega)Y(j\omega)} = \frac{1}{1 + 2(j\omega + \frac{1}{j\omega})(j\omega + \frac{1}{j\omega})} = \frac{-\omega^2}{2\omega^4 - 5\omega^2 + 2}$$

$$|H(j\omega)| = \frac{\omega^2}{|2\omega^4 - 5\omega^2 + 2|} = \begin{cases} \frac{\omega^2}{2\omega^4 - 5\omega^2 + 2}, & \omega < \frac{1}{\sqrt{2}} \\ \frac{\omega^2}{-(2\omega^4 - 5\omega^2 + 2)}, & \frac{1}{\sqrt{2}} < \omega < \sqrt{2} \\ \frac{\omega^2}{2\omega^4 - 5\omega^2 + 2}, & \omega > \sqrt{2} \end{cases}$$

$$\angle H(j\omega) = \angle -\omega^2 - \angle 2\omega^4 - 5\omega^2 + 2 = \begin{cases} \pi, & \omega < \frac{1}{\sqrt{2}} \\ 0, & \frac{1}{\sqrt{2}} < \omega < \sqrt{2} \\ \pi, & \omega > \sqrt{2} \end{cases}$$

(c) Plot the amplitude and phase response of $H(j\omega)$ calculated in part (b).

Magnitude and phase responses are shown in Fig. 2 and Fig. 3, respectively. The magnitude has two vertical asymptote lines at $\omega = \frac{1}{\sqrt{2}}$ and $\omega = \sqrt{2}$. The magnitude is zero at $\omega = 0$. The magnitude also approaches zero for $\omega \rightarrow \infty$. The phase experiences sudden jumps at the frequencies $\omega = \frac{1}{\sqrt{2}}$ and $\omega = \sqrt{2}$.

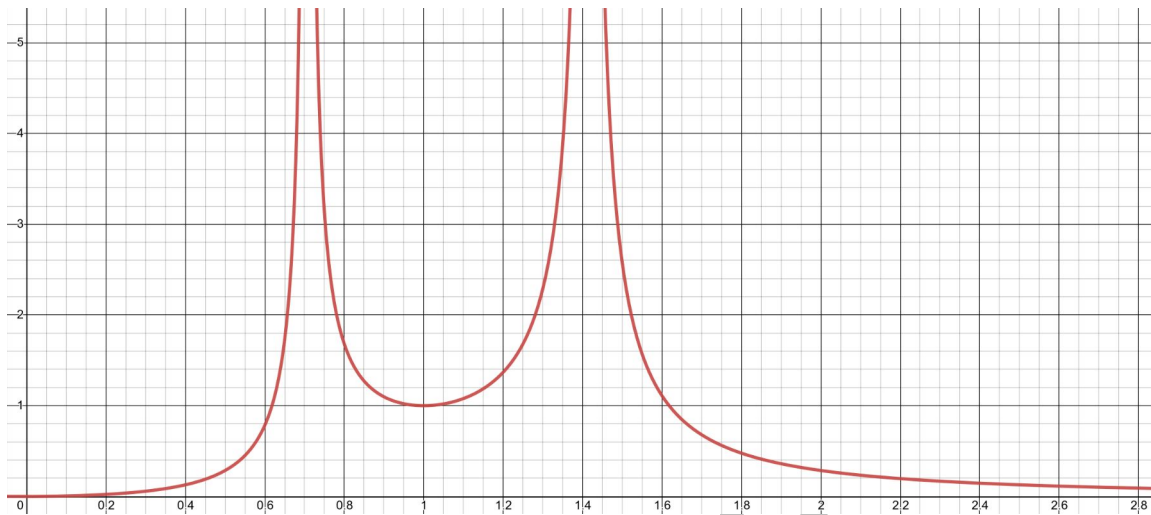


Figure 2: Magnitude response curve.



Figure 3: Phase response curve.

Question 2

Calculate the Thevenin and Norton equivalent circuits seen from port ab in Fig. 4,

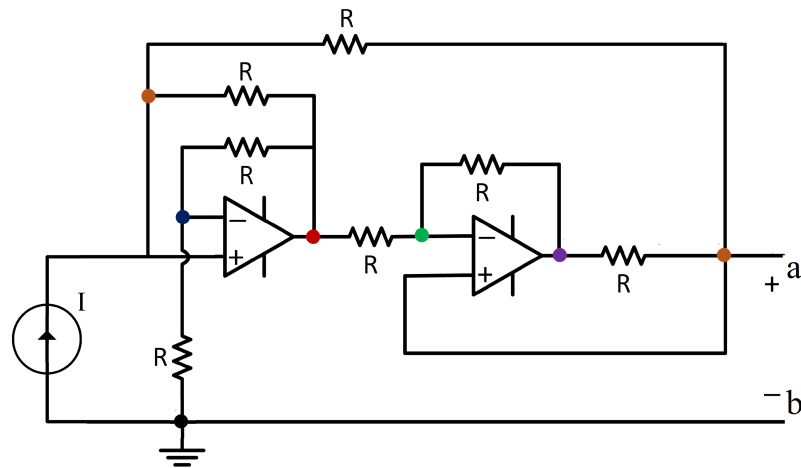


Figure 4: An op-amp circuit.

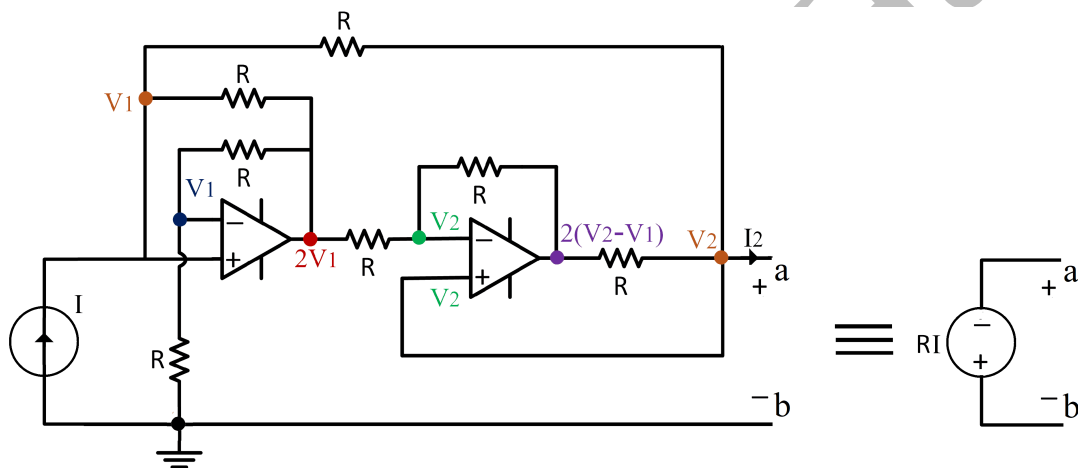


Figure 5: An op-amp circuit.

Consider the annotated circuit shown in Fig. 2. We have,

$$I = \frac{V_1 - 2V_1}{R} + \frac{V_1 - V_2}{R} = -\frac{V_2}{R} \Rightarrow V_2 = -RI = -RI + 0I_2 \Rightarrow V_{oc} = -RI, \quad R_{th} = 0$$

So, the Thevenin equivalent circuit is an alone voltage source as shown in Fig. 5. Consequently, there is no Norton equivalent circuit.

Question 3

The zero-state response of an LTI circuit to the input $x(t) = (e^{-t} - \cos(t) + \sin(t))u(t)$ is $y(t) = 2\sin(t)u(t)$. Find the impulse response, step response, and zero-state response to the input $x_1(t) = e^{-2t} \sin(3t)u(t)$.

We use properties of LTI circuits to find the impulse response.

$$\begin{aligned}
 x(t) &= (e^{-t} - \cos(t) + \sin(t))u(t) \rightarrow y(t) = 2 \sin(t)u(t) \\
 x'(t) &= (-e^{-t} + \sin(t) + \cos(t))u(t) \rightarrow y'(t) = 2 \cos(t)u(t) \\
 x(t) + x'(t) &= 2 \sin(t)u(t) \rightarrow y(t) + y'(t) = 2(\sin(t) + \cos(t))u(t) \\
 x'(t) + x''(t) &= 2 \cos(t)u(t) \rightarrow y'(t) + y''(t) = 2(\cos(t) - \sin(t))u(t) + 2\delta(t) \\
 x''(t) + x'''(t) &= -2 \sin(t)u(t) + 2\delta(t) \rightarrow y''(t) + y'''(t) = 2(-\sin(t) - \cos(t))u(t) \\
 &\quad + 2\delta(t) + 2\delta'(t) \\
 x(t) + x'(t) + x''(t) + x'''(t) &= 2\delta(t) \rightarrow y(t) + y'(t) + y''(t) + y'''(t) = 2\delta(t) + 2\delta'(t) \\
 &\quad \delta(t) \rightarrow h(t) = \delta(t) + \delta'(t)
 \end{aligned}$$

For the step response,

$$x(t) = u(t) \rightarrow s(t) = h(t) * u(t) = (\delta(t) + \delta'(t)) * u(t) = u(t) + \delta(t)$$

And finally, the output corresponding to the input $x_1(t) = e^{-2t} \sin(3t)u(t)$ is

$$y_1(t) = x_1(t) * h(t) = (\delta(t) + \delta'(t)) * x_1(t) = x_1(t) + x_1'(t) = (3e^{-2t} \cos(3t) - e^{-2t} \sin(3t))u(t)$$

Question 4

The one ports \mathcal{N}_1 and \mathcal{N}_2 in Fig. 6 are in sinusoidal steady state. When the one-ports are connected as Fig. 6(a), $V_{aa'} = \sqrt{2}/-45^\circ$, $I_{ab} = 1/0^\circ$ while $V_{aa'} = \sqrt{2}/45^\circ$, $I_{ab'} = 3/0^\circ$ when the one-ports are connected as Fig. 6(b).

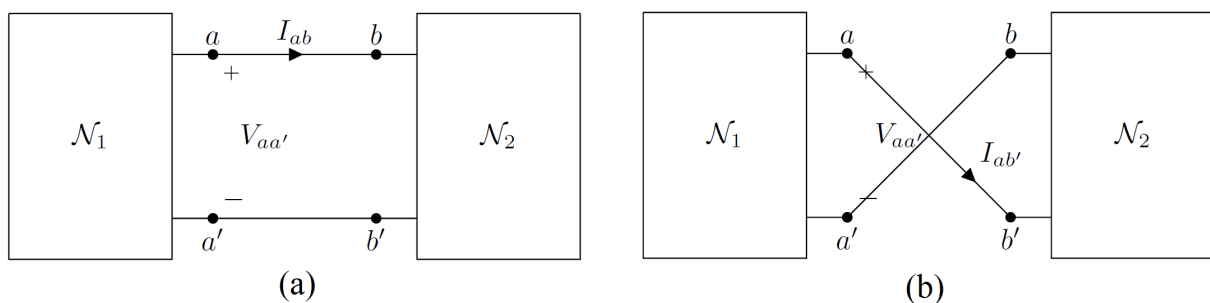


Figure 6: Two one-ports in sinusoidal steady state.

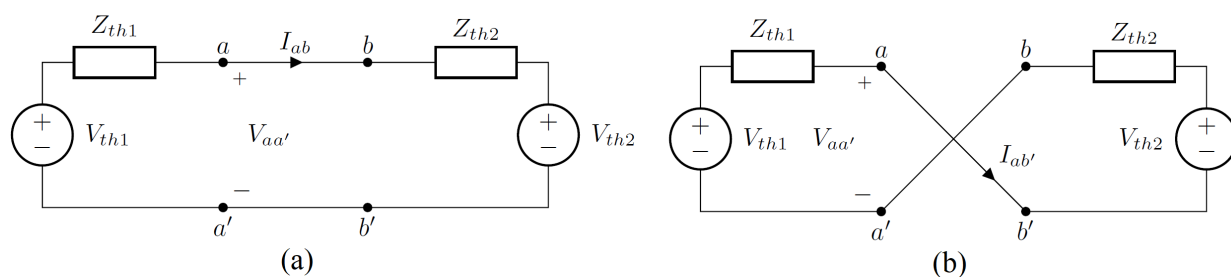


Figure 7: Thevenin equivalent circuits of the one-ports in Fig. 6.

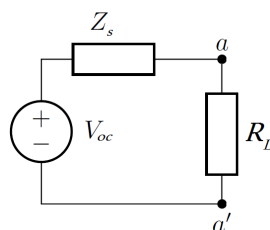


Figure 8: Thevenin equivalent circuit seen from port aa' in Fig. 6(a).

(a) Find the Thevenin equivalent circuits of the two one-ports.

The one ports are replaced with their equivalent Thevenin circuits in Fig. 7. We have,

$$I_{ab1} = \frac{V_{th1} - V_{th2}}{Z_{th1} + Z_{th2}}, \quad V_{aa'1} = V_{th1} - I_{ab1}Z_{th1}$$

$$I_{ab'2} = \frac{V_{th1} + V_{th2}}{Z_{th1} + Z_{th2}}, \quad V_{aa'2} = V_{th1} - I_{ab'2}Z_{th1}$$

So,

$$V_{aa'1} - V_{aa'2} = Z_{th1}(I_{ab'2} - I_{ab1})$$

$$\Rightarrow Z_{th1} = \frac{V_{aa'1} - V_{aa'2}}{I_{ab'2} - I_{ab1}} = \frac{\sqrt{2}\left(\frac{1}{\sqrt{2}} - j\frac{1}{\sqrt{2}}\right) - \sqrt{2}\left(\frac{1}{\sqrt{2}} + j\frac{1}{\sqrt{2}}\right)}{3 - 1} = -j$$

$$V_{th1} = V_{aa'1} + I_{ab1}Z_{th1} = \sqrt{2}\left(\frac{1}{\sqrt{2}} - j\frac{1}{\sqrt{2}}\right) - j = 1 - 2j$$

$$I_{ab1} + I_{ab'2} = \frac{2V_{th1}}{Z_{th1} + Z_{th2}} \Rightarrow Z_{th2} = \frac{2V_{th1}}{I_{ab1} + I_{ab'2}} - Z_{th1} = \frac{2 - 4j}{4} + j = \frac{1}{2}$$

$$V_{th2} = I_{ab'2}(Z_{th1} + Z_{th2}) - V_{th1} = 3\left(\frac{1}{2} - j\right) - 1 + 2j = \frac{1}{2} - j$$

(b) Find the resistance of the resistive load R_L connected between a and a' in Fig. 6(a) that absorbs the maximum average power.

Note that we have a pure resistive load here and we cannot use the simple form of the maximum power transfer theorem. Consider Fig. 8, where that the series combination of the voltage source V_s and impedance Z_s drives the load $Z_L = R_L$. We have,

$$I = \frac{V_s}{Z_s + Z_L} = \frac{V_s}{(R_s + R_L) + jX_s} \Rightarrow P_{avL} = \frac{\Re\{Z_L\}}{2} |I|^2 = \frac{1}{2} \frac{R_L}{(R_L + R_s)^2 + X_s^2} |V_s|^2$$

$$\frac{dP_{avL}}{dR_L} = 0 \Rightarrow (R_L + R_s)^2 + X_s^2 - 2(R_L + R_s)R_L = 0 \Rightarrow R_L = \sqrt{R_s^2 + X_s^2} = |Z_s|$$

The equivalent impedance seen from the port aa' in Fig. 7(a) is shown in Fig. 8 and equal to

$$Z_s = Z_{th1} || Z_{th2} = \frac{-j\frac{1}{2}}{-j + \frac{1}{2}}$$

So, the desired load should have the resistance

$$R_L = |Z_s| = \left| \frac{-j\frac{1}{2}}{-j + \frac{1}{2}} \right| = \frac{\sqrt{5}}{5}$$

(c) Find the maximum power absorbed by the resistive load R_L calculated in the previous part.

We know that

$$Z_s = Z_{th1} || Z_{th2} = \frac{-j\frac{1}{2}}{-j + \frac{1}{2}} = \frac{2}{5} - j\frac{1}{5} = R_s + jX_s$$

Further, using superposition in Fig. 7(a),

$$V_{oc} = \frac{Z_{th2}}{Z_{th1} + Z_{th2}} V_{th1} + \frac{Z_{th1}}{Z_{th1} + Z_{th2}} V_{th2} = \frac{1 + 3j}{-1 + 2j} = 1 - j$$

The maximum power is consumed for $R_L = \frac{\sqrt{5}}{5}$ and equals

$$P_{avL} = \frac{1}{2} \frac{R_L}{(R_L + R_s)^2 + X_s^2} |V_s|^2 = \frac{1}{2} \frac{\frac{\sqrt{5}}{5}}{\left(\frac{\sqrt{5}}{5} + \frac{2}{5}\right)^2 + \left(-\frac{1}{5}\right)^2} |1 - j|^2 = \frac{5}{2\sqrt{5} + 4}$$

Question 5

Let $R_1 = 3\Omega$, $R_2 = 6\Omega$, and $L = \frac{2}{3}\text{H}$ in the first order RL circuit shown in Fig. 9.

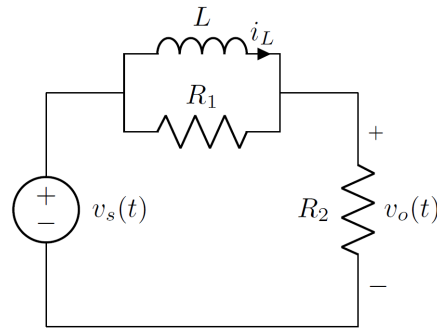


Figure 9: An RL circuit.

(a) Assume that $v_s(t) = e^{-\frac{9}{2}t}u(t)$. Calculate the initial current I_0 of the inductor such that $v_o(t) = 0, t > 0$.

$$v_L = L \frac{di_L}{dt}, \quad i_{R2} = i_L + i_{R1} = i_L + \frac{L}{R_1} \frac{di_L}{dt}, \quad v_o = R_2 i_{R2} = R_2 \left(i_L + \frac{L}{R_1} \frac{di_L}{dt} \right)$$

$$v_s = v_o + v_L = R_2 \left(i_L + \frac{L}{R_1} \frac{di_L}{dt} \right) + L \frac{di_L}{dt} = R_2 i_L + L \left(1 + \frac{R_2}{R_1} \right) \frac{di_L}{dt}$$

$$2 \frac{di_L}{dt} + 6i_L = e^{-\frac{9}{2}t}, t > 0 \Rightarrow i_L = K e^{-3t} - \frac{1}{3} e^{-\frac{9}{2}t}, t > 0$$

$$v_o = 6i_L + \frac{4}{3} \frac{di_L}{dt} = 2K e^{-3t} = 0, t > 0 \Rightarrow K = 0 \Rightarrow i_L(0) = I_0 = K - \frac{1}{3} = -\frac{1}{3}$$

(b) Assume that $v_s(t) = 8 \cos(\sqrt{3}t + \phi)u(t)$ V and let the inductor initial current $i_L(0) = I_0 = 1$ A. Calculate the phase ϕ such that no transient response appears in $i_L(t), t > 0$.

We know that

$$v_s = R_2 i_L + L \left(1 + \frac{R_2}{R_1} \right) \frac{di_L}{dt} \Rightarrow 2 \frac{di_L}{dt} + 6i_L = 8 \cos(\sqrt{3}t + \phi), t > 0$$

$$i_L = i_h + i_p = K e^{-3t} + I_m \cos(\sqrt{3}t + \alpha)$$

Using phasor analysis,

$$2j\sqrt{3}I_p + 6I_p = 8e^{j\phi} \Rightarrow I_p = \frac{8e^{j\phi}}{2j\sqrt{3} + 6} = \frac{8e^{j\phi}}{\sqrt{48}e^{j\frac{\pi}{6}}} = \frac{2}{\sqrt{3}} e^{j(\phi - \frac{\pi}{6})} \Rightarrow i_p = \frac{2}{\sqrt{3}} \cos(\sqrt{3}t + \phi - \frac{\pi}{6})$$

Overall,

$$i_L = K e^{-3t} + \frac{2}{\sqrt{3}} \cos(\sqrt{3}t + \phi - \frac{\pi}{6})$$

To remove the transient part of the response $K = 0$. Further,

$$i_L(0) = I_0 = 1 = K + \frac{2}{\sqrt{3}} \cos(\phi - \frac{\pi}{6}) = \frac{2}{\sqrt{3}} \cos(\phi - \frac{\pi}{6}) \Rightarrow \cos(\phi - \frac{\pi}{6}) = \frac{\sqrt{3}}{2} \Rightarrow \phi = \frac{\pi}{6} + \frac{\pi}{6} = \frac{\pi}{3}$$